XPOW-120AX-CV-U

SPECIFICATION SHEET AND MANUAL 2023





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Series XPOW-120AX-CV-U

Safety Note

Do not operate this product in any manner not specified by Nicslab. Failure to comply with these precautions or with specific warnings or instructions elsewhere in this manual violates safety standards of design, manufacture, and intended use of the instrument. Nicslab assumes no responsibility for any damage caused by mishandling that is beyond normal usage defined in this manual of this product.

Before Applying DC Power Supply

Verify that the DC power supply is in good condition and safe to use. It is imperative to use ONE DC power supply as a source power for this product and the input voltage is no more than 36 V or it can impair this product. Make all connections to the unit before applying power.

Do Not Discard the Instrument Cover Only authorized personnel from Nicslab should remove the instrument cover.

Do Not Alter the Instrument

Do not put any unauthorized parts or modify the instrument without Nicslab approval and warranty.

Caution

This symbol indicates hazard of any operating procedure, practice, or the like that, if not correctly performed or adhered to, could result in damage to the product or loss of important data.

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1. Introduction

Nicslab XPOW-120AX-CV-U system is a versatile multichannel source measurement system. The XPOW-120AX-CV-U supports multiple voltage/current sourcing and voltage/current measurement. The system is suitable for sourcing and measuring low power applications from simple electronic circuits to complex photonic integrated circuits.

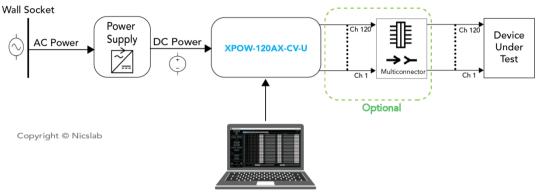
The XPOW-120AX-CV-U provides independent 120 channels controlled by Graphical User Interface (GUI) and Standard Commands for Programmable Instruments (SCPI) through Universal Serial Bus (USB) port. The system has one mode: Constant Voltage (CV) ranging from unipolar 0 - 5 V, 0 - 10 V, 0 - 20 V, and 0 - 34 V (please check your feature selection).

The features for XPOW-120AX-CV-U in details are:

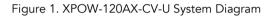
- 16-bits voltage control, see the resolution at Table 4.
- Enable voltage range configuration through software (technology that enables the user to select the output range using software without losing control of the high-resolution feature).
- Flexible output configuration with 16-bit resolution unipolar 0 5 V, 0 10 V, 0 20 V and 0 34 V (*Premium Upgrade*).
- Intuitive GUI.
- Measurement time for single channel: 393 ms.
- Multi-connectors according to your application
- Maximum power output per channel 10 watts.
- Real time voltage reading (16-bits resolution = 1.25 mV).
- Real time current reading (16-bits resolution = 5μ A).
- Save function to create database.
- Upload function to generate the registrable voltage pattern.
- Sequence function for continuous voltage.
- Short circuits protection.
- SCPI command support (Python, Matlab, C# and LabVIEW).
- SCPI Library (Premium Upgrade).
- Windows, Mac, and Linux support.
- USB port with USB line termination, filtering, and electrostatic discharge (ESD) protection.
- Bi-directional electromagnetic interference (EMI) filtering prevents noise from entering/leaving the system.
- Compliance with IEC61000-4-2 ESD Protection for USB Port.

The XPOW-120AX-CV-U needs to be connected with direct current (DC) power first then you can plug into the Device-Under-Test (DUT) or multi-connector. The voltage can be controlled through GUI or SCPI command via USB port.

The system diagram is as follow:



Control System via USB - Embedded



The package should include the following items:

| No | ltem | Qty (pc) | Checklist |
|----|--|----------|-----------|
| 1 | XPOW-120AX-CV-U Box | 1 | |
| 2 | DC power line cord (Red, Black) | 2 | |
| 3 | USB 3.0 cable type B | 3 | |
| 4 | Multi-connector 6 (Optional) | 1 | |
| 5 | USB hub | 1 | |
| 6 | Ribbon rainbow cable | 6 | |
| 7 | USB flash disk | 1 | |
| 8 | Inside USB flash disk: a. GUI b. Specification & Manual c. Test Report d. Serial key (Upgrade) e. XPOW key f. Software Library (Premium) g. Comma-separated values (CSV) template (upload, demo sequence) | 1 | |

2. Hardware

Specification Conditions

The operating and measurement conditions are under the following conditions:

| Table 2. Specification Condit | ions |
|-------------------------------|------|
|-------------------------------|------|

| ltems | Conditions |
|----------------------|---|
| Room Temperature | 0 ~ 40°C |
| Humidity | 5 ~ 80% (No Condensing) |
| Power Supply Input | DC supply max 36 V with effective voltage output range 34 V (potential at red & black DC in). Power supply setting: - Minimum Voltage 10 V. - Minimum Current 2A. Required headroom 1.4 – 2 V. |
| Waterproof/Dustproof | To be operated under room condition |
| Calibration period | 2 years |

Note: To minimize the possibility of overheating the device, it is recommended that the supply voltage value should be the maximum output to be generated + 3 volts. For example, if you have a DUT that needs to be driven by 100 mA current with a voltage of 10 V, then the recommended power supply setting is 10 + 3 Volts which is 13 Volts.

Hardware Requirement

The requirements for the PC/Laptop to be used for this product installation are:

- Resolution Min. 1024 x 768 pixel
- Hard disk Min. 500 MB of available free space (32-bit and 64-bit operating system)
- USB Port USB 2.0
- RAM Min. 2 GB
- CPU 2.4 GHz or faster

Box Descriptions

The box size is 232 (W) x 450 (L) x 102 (H) mm, as the pictures below:

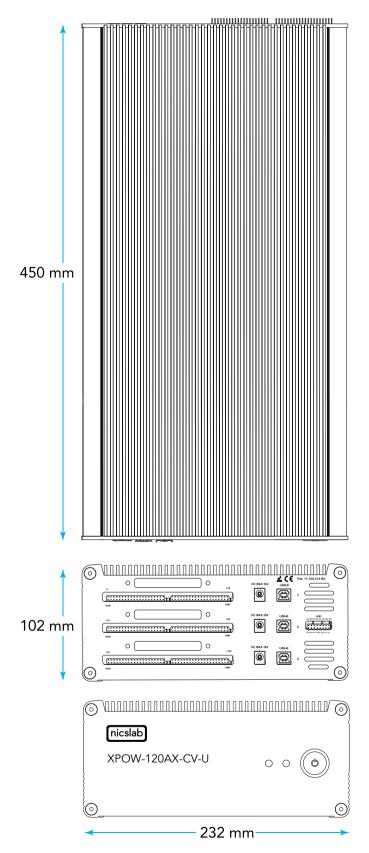


Figure 2. Product Dimension

The details of front and back panel of the box are described below:

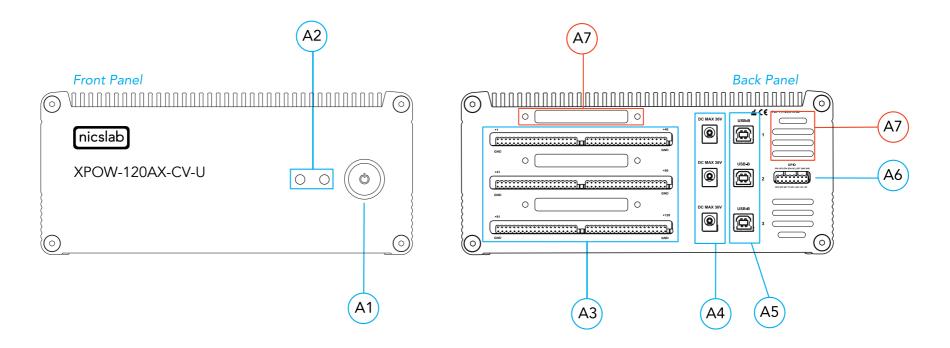


Figure 3. Front, Back and Top View

Note:

| A1 | Power Switch | Turns the instrument on or off. |
|----|-------------------------------------|--|
| A2 | Indicator Light | Green -> Power Indicator. |
| | | Blue -> Serial Transfer Data Active. |
| A3 | Pin Output (40 channels per row) | To connect to Device Under Test (DUT) using cable or multi-connector. |
| | | Row 1: Channel 1 to 40 |
| | | Row 2: Channel 41 to 80 |
| | | Row 3: Channel 81 to 120 |
| Α4 | Input DC Max 36V | Caution Please follow the safety notice on your DC power supply. USE ONLY ONE DC POWER SUPPLY and the input is no more than 36 V. The XPOW will not power up if the current from the power supply is too low (minimum 10 V and 2 A). |
| | | Black cable inserts to negative terminal (0 V) |
| | | Red cable inserts to positive terminal (36 V) |
| A5 | USB-B | USB type B minimum version 2.0. |
| A6 | GPIO | You may use for external control and monitoring direct to microprocessor. |
| A7 | Airflow | For air circulation inside the box. |

XPOW-120AX-CV-U Specifications

The performance specifications of Digital Analog Converter (DAC) <u>voltage</u> are listed in the Table 3 below:

| No | Parameter | Min | Тур | Max | Unit | Test conditions/comments |
|-----|------------------------------------|-------|---------|----------|------------------|--|
| 1 | Resolution | 16 | | | Bits | |
| 2 | Integral nonlinearity (INL) | -1 | ± 0.5 | 1 | LSB | All ranges, except 0 to 40 |
| 3 | Differential Nonlinearity (DNL) | -1 | ± 0.5 | 1 | LSB | Specified 16-bit monotonic |
| 4 | Total unadjusted error | -0.1 | ± 0.01 | 0.1 | %FSR | All ranges |
| 5 | Unipolar offset error | -0.03 | ± 0.015 | 0.03 | %FSR | All unipolar ranges |
| 6 | Unipolar zero-code error | 0 | 0.04 | 0.1 | %FSR | All unipolar ranges |
| 7 | Full-scale error | -0.2 | ± 0.075 | ± 0.2 | %FSR | All ranges |
| 8 | Gain error | -0.1 | ± 0.02 | 0.1 | %FSR | All ranges |
| 9 | Unipolar offset error drift | | ±2 | | ppm of FSR/°C | All unipolar ranges |
| 10 | Gain error drift | | ±2 | | ppm of FSR/°C | All ranges |
| 11 | Output voltage drift over time | | 5 | | Ppm of FSR | $T_A = 40 \text{ °C}$, Full-scale code, 1900 hours |
| DYN | AMIC PERFORMANCE | | | | | |
| 12 | Output Voltage Settling Time | | 12 | | μs | $\frac{1}{4}$ to $\frac{3}{4}$ and $\frac{3}{4}$ to $\frac{1}{4}$ scale setting time to \pm 1 LSB, \pm 10 V range, R _L = 5 k Ω , C _L = 200 pF |
| 13 | Slew Rate | | 4 | | V/µs | All ranges except 0 to 5 V |
| 14 | Power-on glitch magnitude | | 0.3 | | V | Power-down to active DAC output, Midscale code, $R_L = 5 \text{ k}\Omega$, $C_L = 200 \text{ pF}$ |
| 15 | Output noise | | 15 | | µV р-р | 0.1 Hz to 10 Hz, Midscale code, 0 to 5 V range |
| 16 | Output noise density | | 78 | | nV/\Hz | 1 kHz, Midscale code, 0 to 5 V range |
| 17 | AC PSRR | | 1 | | LSB/V | Midscale code, frequency = 60 Hz, amplitude 200 mVpp superimposed on V_{DD} , V_{CC} , or V_{SS} |
| 18 | DC PSRR | | 1 | | LSB/V | |
| 19 | Code change glitch impulse | | 4 | | nV-s | 1 LSB change around the major carrier, 0 to 5 V range |
| 20 | Channel to Channel AC crosstalk | | 4 | | nV-s | 0 to 5 V range. Measured channel at midscale. Full-scale swing on all other channels. |
| 21 | Channel to Channel DC crosstalk | | 0.25 | | LSB | 0 to 5 V range. Measured channel at midscale. All other channels at full-scale. |
| 22 | Digital feedthrough | | 1 | | nV-s | 0 to 5 V range, Midscale code, F _{SCLK} = 1 MHz |

Table 3. DAC Voltage Performance Specification

The voltage control resolution is listed in Table 4 below. The resolution is different for each range. The default range is 40 V (34 V) and can be adjusted in GUI premium version.

| No | Range | Resolution |
|----|-----------------|------------|
| 1 | 0 – 40 V (34 V) | 0.6 mV |
| 2 | 0 – 20 V | 0.3 mV |
| 3 | 0 – 10 V | 150 μV |
| 4 | 0 – 5 V | 76 µV |

Table 4. Voltage Control Resolution

The current value resolution is listed in Table 5 below. The default range is 300 mA and it is a fixed value.

| | ~ | | |
|---------|-----------|-------|------------|
| lable 5 | . Current | Value | Resolution |

| No | Range | Resolution |
|----|------------|------------|
| 1 | 0 – 300 mA | 4.5 µA |

Note: This XPOW is CV only, that means user can only control the voltage, the current value will adjust automatically based on the load connected to each channel

Hardware Installation

This section describes how to install XPOW-120AX-CV-U and how to connect your Device Under Test (DUT) to the output terminals.

The steps are as follow:

- 1. Precondition step: connect to the DC power supply (max 36 V). Make certain that DC power supply is always 'ON'.
- 2. Connect a USB cable to your workstation (PC/Laptop) via USB port.
- 3. Connect XPOW output to the multi-connector (optional, see the manual M1) and your Device Under Test (DUT).
- 4. Install the software/GUI (see the **Error! Reference source not found.** section) from the f lash disk, Dropbox link, and <u>Nicslab website</u>.
- 5. After you install the software/GUI, then the XPOW is ready to use by switching the ON/OFF button at the front panel.

3. Software and Graphical User Interface (GUI)

Software Requirement

The GUI software is suitable with the following operating systems:

- Windows[®] 7 (32-bit, 64-bit).
- Windows[®] 10 (32-bit, 64-bit).
- Windows[®] 11 (64-bit).
- macOS 11 Big Sur.
- Linux Ubuntu

Software Installation

The first step is to copy the GUI file into your hard disk. For Mac, both the GUI and Arduino must be copied inside the 'Application' folder.

Double click the icon below to install the GUI.



At the end step of the installation, check a 'Create a desktop shortcut'.

| Setup - GUT_XPOW Version 4.0.1.9 - × Select Additional Tasks Which additional tasks should be performed? Select the additional tasks you would like Setup to perform while installing GUT_XPOW, then click Next. Additional shortcuts: Create a gesktop shortcut Back Next Cancel | | | | _ | ~~~~ |
|---|---|---------------------|--------------|-----------|-------|
| Which additional tasks should be performed? Select the additional tasks you would like Setup to perform while installing GUT_XPOW, then click Next. Additional shortcuts: Create a gestop shortcut | Setup - GUI_XPOW version 4.0.1.9 | | — | | × |
| Select the additional tasks you would like Setup to perform while installing GUT_XPOW, then click Next. Additional shortcuts: Create a gesistop shortcut | Select Additional Tasks | | | | FX |
| Additional shortcuts: | Which additional tasks should be performed? | | | | (m) |
| Additional shortcuts: | | | | | |
| Create a gesktop shortcut | Select the additional tasks you would like Setup to perform whi | le installing GUI_X | POW, then cl | ick Next. | |
| | Additional shortcuts: | | | | |
| Back Next Cancel | Create a desktop shortcut | | | | |
| Back Next Cancel | | | | | |
| Back Next Cancel | | | | | |
| Back Next Cancel | | | | | |
| Back Next Cancel | | | | | |
| Back Next Cancel | | | | | |
| Back Next Cancel | | | | | |
| Back Next Cancel | | | | | |
| Back Next Cancel | | | | | |
| Back Next Cancel | | | | | |
| Back Next Cancel | | | | | |
| Back Next Cancel | | | | | |
| <u>B</u> ack <u>N</u> ext Cancel | | | | | |
| | | Back | Next | C | ancel |

Double click the executable GUI icon (as below) on your desktop to launch the GUI.



How to Detect Which COM Is Used (Windows only)

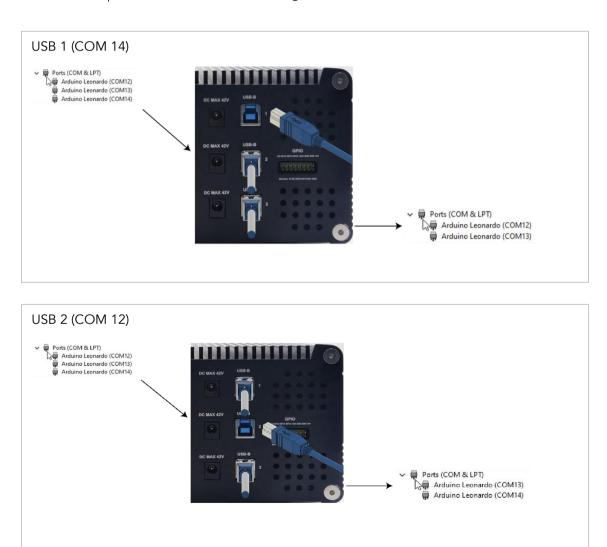
1. Click Start . Type "Device Manager", and then click Device Manager.

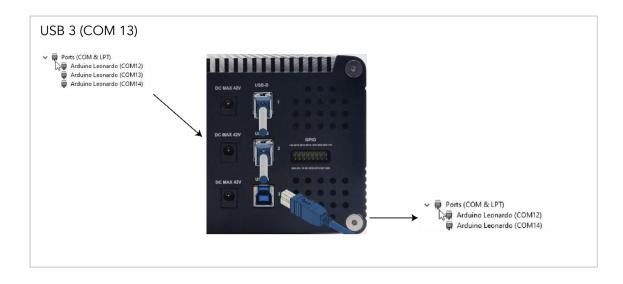


2. Find Ports (COM & LPT).

> 🛱 Ports (COM & LPT)

- 3. When XPOW connects on the computer, there are 3 (three) ports Arduino Leonardo detected with COM number as shown below.
 - ✓ Ports (COM & LPT)
 ↓ Arduino Leonardo (COM12)
 Arduino Leonardo (COM13)
 Arduino Leonardo (COM14)
- 4. To know the COM port for each USB port, you may unplug the USB ports one by one and compare with the COM port listed on the Device Manager.





Graphical User Interface (GUI)

Start the XPOW by pressing the ON button, then you can control it by GUI, the display details are on the next page.

Note: You can also launch the GUI through programming languages such as Python, C#, LabVIEW and Java.

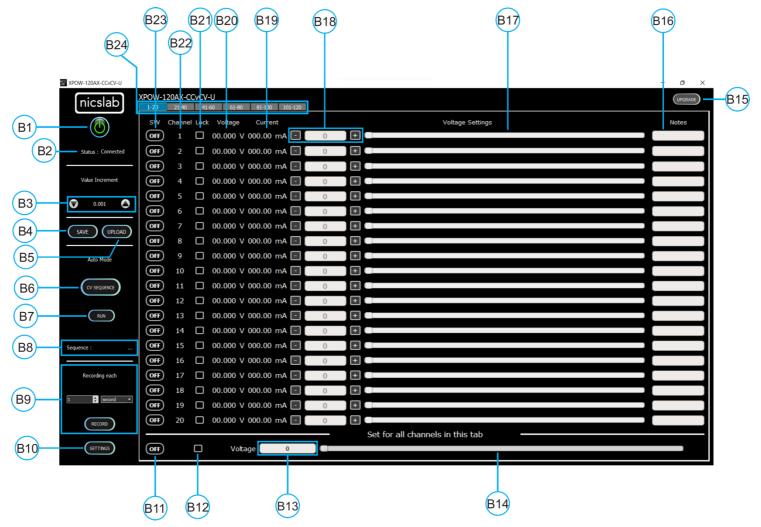


Figure 4. GUI

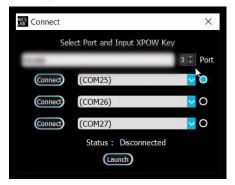
Note:

| Callout | Description |
|---------|--|
| B1 | ON/OFF Switch |
| B2 | Status of connection |
| B3 | Increment Settings |
| B4 | Save File Button - Premium Feature |
| B5 | Upload File Button - Premium Feature |
| B6 | Auto Feature Sequence: Upload Table Button CV Mode - Premium Feature |
| B7 | Auto Feature: Run Button CV Mode - Premium Feature |
| B8 | Name of the Sequence - Premium Feature |
| B9 | Record Data Button - Premium Feature |
| B10 | Setting for: Set Limit voltage and current values - Premium Feature V Range (16-bit precision for every range of voltages: 5, 10, 20, 34 V) - Premium Feature Set the Reading speed of Voltage and Current (Fast, Medium, Slow) - Premium Feature |
| B11 | ON/OFF Button for the current Tab |
| B12 | Enable/Disable (Lock) Channel Controller for all channels in the current tab |
| B13 | Text area to set the voltage for all channels in the current tab |
| B14 | Slider to set the voltage for all channels in the current tab |
| B15 | Upgrade Button |
| B16 | Notes - Premium Feature |
| B17 | Voltage Settings Slider |
| B18 | Voltage Value Based on Increment Setting |
| B19 | Current Value |
| B20 | Voltage Value |
| B21 | Enable/Disable (Lock) Channel Controller |
| B22 | Number of channels |
| B23 | ON/OFF Button per Channel |
| B24 | Tab Channel |

Initializing the GUI

This section shows how to initialize the GUI:

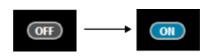
- 1. Launch the GUI by double clicking the executable GUI icon.
- 2. When you launch the GUI for the first time, input the 'XPOW Key' and put the correct 'COM' port.



3. Press switch button (B1) on GUI to connect it with the XPOW.



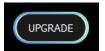
4. Turn ON (B23) on each channel to input voltage values.



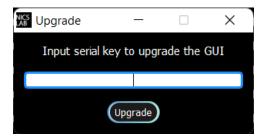
Premium Upgrade

This section shows how to upgrade the GUI to enable advanced features.

1. Press the upgrade button (B15) at the top right corner of the window



2. After the upgrade window opened, input the Premium Upgrade Key.



3. If your Premium Upgrade Key is valid, you will get a message that indicates a successful upgrade.



4. You can use several features that were previously locked.

| XPOW-120AX-CCvCV-U | | - 0 × |
|--------------------|---|-------|
| nicslab | XPOW-120AX-CCVCV-U 1:20 21:40 41:60 61:60 81:100 101:120 | |
| | SW Channel Lock Voltage Current Voltage Settings | |
| | · OFF 1 □ 00.000 V 000.00 mA = 0 	 . | |
| Status : Connected | 0 FF 2 □ 00.000 V 000.00 mA 🗉 0 🕨 □ | |
| | OFF 3 □ 00.000 V 000.00 mA □ 0 	 • □ | |
| Value Increment | 0FF) 4 □ 00.000 V 000.00 mA 🖃 0 💽 🕶 | |
| 👽 0.001 🕥 | · OFF 5 □ 00.000 V 000.00 mA 🖃 0 主 0 | |
| | · OFF 6 □ 00.000 V 000.00 mA 🖃 0 💽 🕶 | |
| | 0FF 7 □ 00.000 V 000.00 mA □ 0 | |
| | · OFF 8 □ 00.000 V 000.00 mA = 0 	 • □ | |
| Actor Poste | 9 □ 00.000 V 000.00 mA 🖃 0 💽 🕶 | |
| | · OFF 10 □ 00.000 V 000.00 mA = 0 	 ● | |
| (| · OFF 11 □ 00.000 V 000.00 mA 🖃 0 💽 ● | |
| | 0FF 12 00.000 V 000.00 mA 🗐 0 F | |
| | 0FF 13 00.000 V 000.00 mA 🗉 0 F 🗆 | |
| | 0FF) 14 □ 00.000 V 000.00 mA □ 0 | |
| Stepence | 0FF 15 □ 00.000 V 000.00 mA □ 0 | |
| | 0FF 16 □ 00.000 V 000.00 mA 🖃 0 🕨 | |
| Recording each | 0FF 17 □ 00.000 V 000.00 mA □ 0 | |
| | 0FF 18 00.000 V 000.00 mA 🗉 0 | |
| | 0FF 19 00.000 V 000.00 mA 🖃 0 | |
| (ucces) | 0FF 20 00.000 V 000.00 mA 🗉 0 F | |
| | Set for All Channels in this Tab | |
| | OF 1-20 Votage COO | |
| | | |

| XPOW-120AX-CCvCV-U | • | - o × |
|--------------------|--|-------|
| nicslab | XPOW-120AX-CCvCV-U 120 2140 4140 5140 81100 101120 | |
| | SW Channel Lock Voltage Current Voltage Settings 00F7 1 00.000 V 000.00 mA 0 | Notes |
| Status : Connected | OFF 2 □ 00.000 V 000.00 mA □ 0 ■ 0 | |
| | OFF 3 00.000 V 000.00 mA 🗉 💿 🔹 | |
| Value Increment | 00 € 4 □ 00.000 V 000.00 mA □ 0 € 0 | |
| 0.001 | | |
| | 00F 6 00.000 V 000.00 mA 1 0 I 0 00F 7 00.000 V 000.00 mA 1 0 I 0 | |
| SAVE UPLOAD | | |
| Auto Mode | OFF 9 □ 00.000 V 000.00 mA □ 0 | |
| | 0FF 10 00.000 V 000.00 mA 🗉 0 💽 🖬 | |
| CV SEQUENCE | 00F 11 □ 00.000 V 000.00 mA □ 0 ■ 0 | |
| \square | 007 12 00.000 V 000.00 mA Image: Comparison of the comparison of | |
| RUN | (0ff) 13 00.000 V 000.00 mA 0 Image: Comparison of the comparison | |
| Sequence : | | |
| | 00F 16 🗆 00.000 V 000.00 mA 🗉 🚺 0 | |
| Recording each | 00F 17 □ 00.000 V 000.00 mA = 0 ■ | |
| 1 Second - | | |
| | | |
| RECORD | Set for all channels in this tab | |
| SETTINGS | OFF D Votage 0 | |

The next few sections are the advanced features that are enabled after upgrading the GUI.

Constant Voltage (CV) Mode

This section shows how to do CV mode according to your aim:

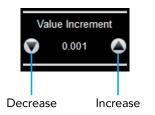
To do CV mode, you need to adjust the voltage value on (B18) or slider (B17).

Important note: When you input manually the values, always press 'Enter'.

| XPOW-120AX-CV-U | | | | - | |
|--------------------|---|----------------------|------------------|---|---------|
| nicslab | XPOW-120AX-CV-U | B18 | B17 | | Upgrade |
| | 1 - 20 21 - 40 41 - 60 61 - 80 | 0 81 - 100 101 - 120 | | | |
| | SW Channel Lock Voltage Current | | Voltage Settings | | Notes |
| | OFF 1 □ 00.000 V 000.00 mA - OFF 2 □ 00.000 V 000.00 mA - | | | | _ |
| Status : Connected | OFF 2 00.000 ∨ 000.00 mA - (OFF) 3 00.000 ∨ 000.00 mA - | | | | |
| Status ; Connected | OFF 4 00.000 V 000.00 mA | | | | |
| | 0FF 5 00.000 V 000.00 mA | | | | |
| Value Increment | OFF 6 🗌 00.000 V 000.00 mA - | 0 | | | |

Value Increment Setting

In this setting, the value of the voltage and current can be incrementally changed from 0.001 to 1. Click the arrows to increase and decrease the value increment (B3).



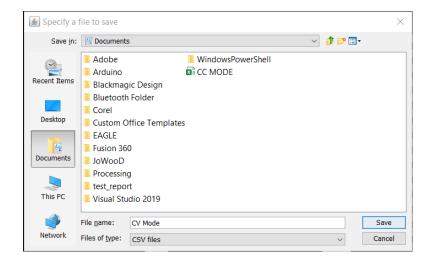
Save and Upload

The CSV file (.csv) resulting from the Save function can be uploaded again through the Upload button (B5). You may also create your own CSV file of voltage and current and upload it later.

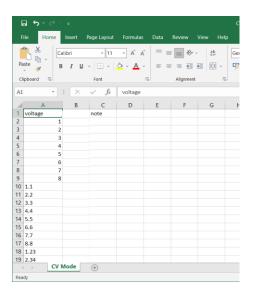
1. To save the configuration, click the 'Save' button (B4).



2. Select a directory and write the file name.



- 3. The file will be saved as a .csv file.
- 4. Check the .csv file that you have saved.



The voltage, current, and notes are recorded. If the file doesn't appear to have saved data from all channel, consider trying to open the file with another program, like Notepad, for further inspection.

5. To upload the configuration, click the 'Upload' button (B5).



6. Choose and open the intended file.

| File Home Share View | | | | ^ |
|---|---|---|--|---|
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| Vicslab Dropbox | WindowsPowerShell CV Mode | | 22/09/2021 14:07 04/02/2022 14:32 | File folder Microsoft Excel Co |
| | | | | |

7. It will upload the configuration like the previous configuration.

| XPOW-120AX-CV-U | | | | – o x |
|--------------------|---|-----------------------------------|------------------|---------|
| nicslab | XPOW-120AX-CV-U | B18 61 - 80 81 - 100 101 - 120 | B17 | Upgrade |
| | SW Channel Lock Voltage Current OFF 1 00.000 V 000.000 V OFF 2 00.000 V 000.000 V | | Voltage Settings | Notes |
| Status : Connected | OFF 3 00.000 V 000.00 f OFF 4 00.000 V 000.00 f | | | |
| Value Increment | OFF 5 00.000 V 000.000 OFF 6 00.000 V 000.000 | | | |

Sequence Automation

The sequence is the setting that automates the determined values of voltage (V) given the certain Delay Time (in millisecond).

1. The template of sequence is given, then you need to input your intended values of CV Sequence (from 0 to 34 V), and Delay Time (in millisecond). Set the delay time to more than 2 seconds to have more accurate values. To have a faster response (switching time) you can set via SCPI command).

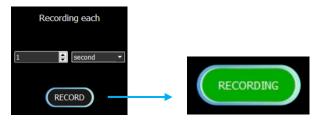
| | Α | В | С | D | E | F | G | Н | 1 | J | |
|----|------------|-------|-------|-------|-------|-------|-------|-------|-------|----------|----|
| 1 | | Seq 1 | Seq 2 | Seq 3 | Seq 4 | Seq 5 | Seq 6 | Seq 7 | Seq 8 | Note | |
| 2 | Delay Time | 6000 | 5478 | 4912 | 3409 | 4213 | 5902 | 6012 | | | |
| 3 | Channel 1 | 5 | 50 | 0 | 100 | 150 | 150 | 0 | 300 | Fan1 | |
| 4 | Channel 2 | 10 | 50 | 0 | 100 | 160 | 150 | 0 | 300 | Fan2 | |
| 5 | Channel 3 | 15 | 50 | 0 | 100 | 170 | 150 | 0 | 300 | Motor1 | |
| 6 | Channel 4 | 20 | 50 | 0 | 100 | 180 | 150 | 0 | 300 | Motor2 | (B |
| 7 | Channel 5 | 25 | 50 | 0 | 100 | 190 | 150 | 0 | 300 | Sensor1 | e |
| 8 | Channel 6 | 30 | 50 | 0 | 100 | 200 | 150 | 0 | 300 | Sensor2 | |
| 9 | Channel 7 | 35 | 50 | 0 | 100 | 210 | 150 | 0 | 300 | Sensor3 | |
| 10 | Channel 8 | 40 | 50 | 0 | 100 | 220 | 150 | 0 | 300 | Not Used | |

Note:

- A. Template given for CV sequences.
- B. Input your intended values according to the modes (CV: 0 34 V).
- 2. Choose CV Sequence mode (B6). When you click, say CV sequence you need to open the corresponding CSV sequence file.
- 3. After uploading, choose sequence mode by clicking 'Run' (B7). It will run CV Sequence depends on the .csv file that you uploaded before.

Record

'Record' (B9) keeps data on voltage and current values. You can choose how often the data is stored in a unit of time. The default value is the data will be stored each one second. The record starts by the time you click the Record button and will finish when you click again the same button.



Click the same button to stop Recording. After that, put the file in any directory

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| File name: record | 120d | | | ~ |
| Save as type: CSV Fil | es (*.csv) | | | ~ |
| ∧ Hide Folders | | | Save | Cancel |

This is the output of the recorded file

| | ئ ہے د | | | | | | | | | | | | | | | | |
|-------------|---------------------|--------------|--------------------------|-----------|---------------|-------|----------|-------------------|--------|------------------------------|----------------------------|--|-----------|----------------------------|---|----------------|-----------|
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| Get Data | | Existi | nt Sources ng Connect | Ref | resh | | | 2↓ ZAZ Z↓ Sort | Filter | Clear Reapply Advanced | Text to Columns Data | III III | Analysis | Forecast Sheet ecast | Croup Group Ungro Subto Outli | up ∽ "∃ tal | |
| 1 | × | · | Time | Stamp | | | | | | | | | | | | | |
| | A B | С | D | E | F | G | H | 1 | J | K | L | M | N | 0 | Р | Q | R |
| Т | ime Stamp Voltage[: |] Current[1] | Notes | Voltage[2 | [] Current[2] | Notes | Voltage[| 3] Current[3] | Notes | Voltage[4 |] Current[4 | Notes | Voltage[5 | 6] Current[5] | Notes | Voltage[6 | 5] Currer |
| | 20:29:19 1.111 V | 9.1 mA | Fan1 | 1.053 V | 9.17 mA | Fan2 | 1.125 V | 9.12 mA | Motor1 | 1.107 V | 9.12 mA | Motor2 | 1.099 V | 9.07 mA | Sensor1 | 1.112 V | 9.05 n |
| | 20:29:20 1.111 V | 9.07 mA | Fan1 | 1.053 V | 9.17 mA | Fan2 | 1.125 V | 9.12 mA | Motor1 | 1.107 V | 9.12 mA | Motor2 | 1.099 V | 9.07 mA | Sensor1 | 1.112 V | 9.05 n |
| | 20:29:21 1.111 V | 9.1 mA | Fan1 | 1.053 V | 9.17 mA | Fan2 | 1.125 V | 9.12 mA | Motor1 | 1.107 V | 9.12 mA | Motor2 | 1.1 V | 9.07 mA | Sensor1 | 1.112 V | 9.05 n |
| | 20:29:22 1.111 V | 9.1 mA | Fan1 | 1.053 V | 9.17 mA | Fan2 | 1.125 V | 9.12 mA | Motor1 | 1.107 V | 9.12 mA | Motor2 | 1.099 V | 9.07 mA | Sensor1 | 1.112 V | 9.05 n |
| | 20:29:23 1.111 V | 9.1 mA | Fan1 | 1.053 V | 9.17 mA | Fan2 | 1.125 V | 9.12 mA | Motor1 | 1.107 V | 9.12 mA | Motor2 | 1.1 V | 9.07 mA | Sensor1 | 1.112 V | 9.05 n |
| | 20:29:24 1.111 V | 9.1 mA | Fan1 | 1.053 V | 9.17 mA | Fan2 | 1.125 V | 9.12 mA | Motor1 | 1.107 V | 9.12 mA | Motor2 | 1.1 V | 9.07 mA | Sensor1 | 1.112 V | 9.05 n |
| 1 | 20:29:25 8.716 V | 71.8 mA | Fan1 | 1.054 V | 9.17 mA | Fan2 | 1.125 V | 9.12 mA | Motor1 | 1.107 V | 9.12 mA | Motor2 | 1.1 V | 9.07 mA | Sensor1 | 1.112 V | 9.05 n |
| | 20:29:26 8.716 V | 71.8 mA | Fan1 | 1.054 V | 9.17 mA | Fan2 | 1.125 V | 9.12 mA | Motor1 | 1.107 V | 9.12 mA | Motor2 | 1.1 V | 9.07 mA | Sensor1 | 1.112 V | 9.05 n |
|) | 20:29:27 8.716 V | 71.8 mA | Fan1 | 1.054 V | 9.17 mA | Fan2 | 1.125 V | 9.12 mA | Motor1 | 1.107 V | 9.12 mA | Motor2 | 1.1 V | 9.07 mA | Sensor1 | 1.112 V | 9.05 n |
| 1 | 20:29:28 8.716 V | 71.8 mA | Fan1 | 8.699 V | 76.37 mA | Fan2 | 1.125 V | 9.12 mA | Motor1 | 1.109 V | 9.15 mA | Motor2 | 1.1 V | 9.07 mA | Sensor1 | 1.112 V | 9.05 n |
| 2 | 20:29:29 8.717 V | 71.8 mA | Fan1 | 8.699 V | 76.35 mA | Fan2 | 1.125 V | 9.12 mA | Motor1 | 1.109 V | 9.15 mA | Motor2 | 1.1 V | 9.07 mA | Sensor1 | 1.112 V | 9.05 n |
| 3 | 20:29:30 8.717 V | 71.8 mA | Fan1 | 8.699 V | 76.35 mA | Fan2 | 1.125 V | 9.12 mA | Motor1 | 1.109 V | 9.15 mA | Motor2 | 1.1 V | 9.07 mA | Sensor1 | 1.112 V | 9.05 n |
| 4 | 20:29:31 8.717 V | 71.8 mA | Fan1 | 8.699 V | 76.35 mA | Fan2 | 1.156 V | 9.35 mA | Motor1 | 1.109 V | 9.12 mA | Motor2 | 1.1 V | 9.07 mA | Sensor1 | 1.112 V | 9.05 n |
| 5 | 20:29:32 8.717 V | 71.8 mA | Fan1 | 8.699 V | 76.35 mA | Fan2 | 1.372 V | 11.15 mA | Motor1 | 1.109 V | 9.15 mA | Motor2 | 1.1 V | 9.07 mA | Sensor1 | 1.112 V | 9.05 n |
| 6 | 20:29:33 8.717 V | 71.8 mA | Fan1 | 8.699 V | 76.35 mA | Fan2 | 1.372 V | 11.15 mA | Motor1 | 1.475 V | 12.2 mA | Motor2 | 1.1 V | 9.07 mA | Sensor1 | 1.114 V | 9.05 n |
| 7 | 20:29:34 8.716 V | 71.8 mA | Fan1 | 8.699 V | 76.35 mA | Fan2 | 1.372 V | 11.15 mA | Motor1 | 1.474 V | 12.2 mA | Motor2 | 1.1 V | 9.07 mA | Sensor1 | 1.112 V | 9.05 n |
| 3 | 20:29:35 8.717 V | 71.8 mA | Fan1 | 8.699 V | 76.35 mA | | 1.372 V | 11.15 mA | | 1.475 V | 12.2 mA | Motor2 | 2.148 V | 17.75 mA | | 1.114 V | 9.05 n |
| 9 | 20:29:36 8.716 V | 71.77 mA | | 8.699 V | 76.35 mA | | 1.372 V | 11.15 mA | | 1.475 V | 12.2 mA | Motor2 | 2.441 V | 20.22 mA | | 1.72 V | 13.82 |
| 0 | 20:29:37 8.716 V | 71.77 mA | | 8.699 V | 76.35 mA | | 1.372 V | 11.15 mA | | 1.475 V | 12.2 mA | Motor2 | 2.441 V | 20.22 mA | | 3.7 V | 30.27 |
| 1 | 20:29:38 8.716 V | 71.77 mA | | 8.699 V | 76.35 mA | | 1.372 V | 11.15 mA | | 1.475 V | 12.2 mA | Motor2 | 2.441 V | 20.22 mA | | 3.7 V | 30.27 |
| | record120 | | | | | | | | | 1 | | | | | | | • |

Settings

Click the 'Settings' button (B10).



The 'Settings' feature consists of:

• Set voltage limit is to limit the control voltage (B17, B18, and B20).

| Set Maximum Limit Settings for Each Channel Set Limit Set Limit 1 0.00 2 2.2 4 0.00 3 2.5 7 6.6 7 0.6 7 0.6 7 0.6 7 0.6 7 0.6 7 0.6 7 0.6 7 0.6 7 0.6 7 0.6 7 0.6 7 0.6 8 1.0 8 1.0 9 8.8 9 8.8 9 8.8 9 8.8 9 8.8 9 8.8 9 1.0 9 1.0 9 1.0 9 1.0 9 1.0 9 1.0 10 2.5 10 2.5 10 2.0 | nit Voltage |
|--|-------------|
| XPOW-120AX-CV-U | – 🗆 X |
| XPOW-120AX-CV-U 1 - 20 21 - 40 41 - 60 61 - 80 81 - 100 101 - 120 | Upgrade |
| SW Channel Lock Voltage Current Voltage Settings | Notes |
| OFF 1 0.806 V 006.43 mA 0.800 • OFF 2 1.222 V 010.13 mA 1.200 • | |
| Save Upload Orr 3 2.519 v 019.90 mA 2.500 • | |
| OFF 4 □ 3.320 V 026.28 mA □ 3.300 • | • |
| Auto Mode OFF 5 4.556 V 037.17 mA 4.550 • | |

Important note: When you input the values, always press 'Enter'.

• Set range for voltage values where you can choose the voltage range to limit the voltage values (B17, B18, and B20), the range of voltages are 5 V, 10 V, 20 V and 34 V. Each range has 16-bit precision.

| Set Maximum Limit Settings For Each Cha | nnel × | | |
|---|---|------------------|---------|
| | nnei A | | |
| | | | |
| | 10 18 11 25 5 10 18 16 2.5 5 10 18 | | |
| 2 2.5 5 10 18 7 2.5 5 | 10 18 12 2.5 5 10 18 17 2.3 5 10 18 | | |
| | 10 18 13 25 5 10 18 18 2.5 5 10 10 10 18 14 25 5 10 18 19 2.5 5 10 16 | | |
| 5 2.5 5 10 18 10 2.5 5 | | | |
| | | | |
| | | | |
| | | | |
| | | | |
| TPOW-120AX-CV-U | | | – 🗆 X |
| | XPOW-120AX-CV-U | | Upgrade |
| nicslab | 1 - 20 21 - 40 41 - 60 61 - 80 81 - 100 10 | 11 - 120 | |
| | SW Channel Lock Voltage Current | Voltage Settings | Notes |
| \bigcirc | OFF 1 □ 2.489 V 019.98 mA - 2.500 • | | |
| | OFF 2 5.004 V 041.06 mA 5.000 | | |
| Save Upload | OFF 3 □ 5.007 V 040.58 mA - 5.000 • | | |
| | . OFF 4 🗆 10.031 V 081.86 mA - 10.000 • | | |
| | OFF 5 14.996 V 040.83 mA 5.000 + | | |
| Auto Mode | | | |

Important note: When you input the values, always press 'Enter'.

• Set reading speed for voltage. There are three options which is Fast, Medium, and Slow. Faster options can make conversion time smaller but the results noisier.

| | 📓 Settings | x |
|---------------|------------------------|---------------|
| | Set Limit Set Range Re | leading Speed |
| Reading Speed | Fast Mediu | um Słów |

Important note: When you input the values, always press 'Enter'.

4. Operating XPOW through SCPI command

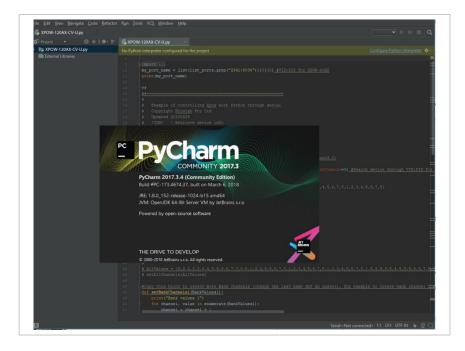
This section set guidelines to help you develop program for any language suits you best. The example language program is written in Python.

Python Installation (Example)

Please follow the steps below for dynamic programming using the SCPI command through Python via serial.

The following Python and packages need to be installed:

- 1. Python 2.7 or Python 3.X (download and install the latest version from <u>www.python.org</u>). *Tested with Python 3.7.
- 2. PyCharm 2017.3.4 or the latest version (download and install the latest version from https://www.jetbrains.com/pycharm/)



Run Python Code (Example)

To run the Python code please follow the steps below:

1. Open PyCharm software and open file example (e.g XPOW-120AX-CV-U.py).

 Configure Python interpreter see figure below by clicking Configure Python Interpreter link on the top right-hand corner of the code, or in File >> Settings >> Project Interpreter in Windows or Preference >> Project Interpreter in Mac. Select Python 2.7 or Python 3.X in Project Interpreter list.

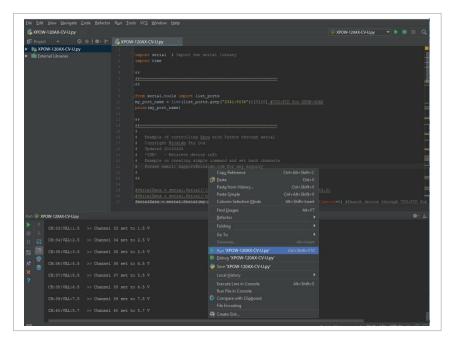
| | Project: XPOW-120AX-CV-U.py | > Project Interpreter 🛛 🖪 For current project | |
|--|---------------------------------|---|----------|
| Appearance & Behavior | Project Interpreter: 🛛 🍓 Python | | |
| Кеутар | | | |
| ▶ Editor | Package | | Latest + |
| Plugins | | | |
| Version Control | blessings | | |
| | | | |
| Project: XPOW-120AX-CV-U.py | | | |
| | pip pyqt5-installer | | |
| | pyserial | | |
| Build, Execution, Deployment | qtgui | | |
| Languages & Frameworks | | | |
| | wget | | |
| Tools | wsgiref | | |
| | | | |
| | | | |

3. Install additional packages: enum34, pip, pyserial, setup tools by clicking + button, search and install all the packages.

| Q* Q* pvSerial | Available Packages | |
|---|---|--|
| | | |
| Ap PySerialization Ke cypyserialize pySerialize pyserialize pyserialize pyserializer pyserializer pyserializer pyserializer | Description Python Serial Port Extension Version 3.4 Author Chris Liechti mallo-cliechti@gemc.net https://github.com/gyserial/pyserial | |

4. Select Python Configuration and choose the file name.

5. Run the file by clicking the green arrow button on the top right corner to test the XPOW (Please refer to the code and SCPI commands references.



Python Function (Example)

1. <u>Constant Voltage Calibration for single channel</u>

Calibration work by applying voltage below the limit that we set in this function

```
cvCalibrationSingleChannel(channel, vcal)
```

channel (int): channel number

vcal (float): 0 - 34 V

Example:

Calibration with DUT connected to channel 1, voltage limit 0.5 V.

```
cvCalibrationSingleChannel(1, 0.5)
```

2. <u>Constant Voltage Calibration for all channel</u>

Calibration work by applying voltage below the limit that we set in this function

cvCalibrationAllChannel(vcal)

vcal (float array): 0 - 34 V

3. Set ON for single channel

```
setChannel(channel, voltageVal)
channel (int): channel number
voltageVal (float): 0 - 34 V
```

4. <u>Set ON for all channels</u>

```
setVoltage1Channels(AllVValues) for channels 1 - 40
setVoltage2Channels(AllVValues) for channels 41 - 80
setVoltage3Channels(AllVValues) for channels 81 - 120
AllVValues (float array): voltage values in array(V)
Example:
AllCValues = [100, 150, 100, 50, 200, 10, 10, 200] * 5
AllVValues = [20.1, 2.5, 13.0, 4, 5, 10.5, 9.5, 22] * 5
```

5. <u>Set Range for all channels</u>

setRange1Channels(AllRangeValues) for channels 1 - 40
setRange2Channels(AllRangeValues) for channels 41 - 80
setRange3Channels(AllRangeValues) for channels 81 - 120
AllRangeValues (Int array): voltage range index values in array
Array Index:
0: 0 - 5 V
1: 0 - 10 V
2: 0 - 20 V
4: 0 - 34 V (with 36 power supply)
Example:
AllRValues = [1, 0, 1, 0, 2, 1, 0, 2] * 5

6. Set GPIO digital output

setGPIO(index, value)
Index (int): Index of GP pin (12, 13, 16, 19, 26)
Value (string) : "HIGH" or "LOW"
Example:
Set GP26 output to digital high
setGPIO(26, "HIGH")

7. Set Measurement Config

for channels 1 - 40: measurementConfig1(voltConvTime, currConvTime, averaging) for channels 41 - 80: measurementConfig2(voltConvTime, currConvTime, averaging) for channels 81 - 120: measurementConfig3(voltConvTime, currConvTime, averaging) voltConvTime(Int uS): Voltage measurement conversion time averaging(int): count of sample to be averaged

8. <u>Set OFF for single channel</u>

setOff(channel)
channel (int): channel number

9. Set OFF for all channels

setOffAllChannels(maxChannel)
maxChannel (int): maximum number of channels in XPOW

10. Read real-time value for single channel

readChannel(channel)
channel (int): channel number

```
11.<u>Read real-time value for all channels</u>
```

readCommand1(maxChannel) for channels 1 - 40
readCommand2(maxChannel) for channels 41 - 80
readCommand3(maxChannel) for channels 81 - 120
maxChannel (int): maximum number of channels in XPOW

12. Automatic Setting for One Channel

Change and record the value in one channel for every duration time. The result will be saved as CSV file.

```
sweepOne(channel, seqValueV, duration)
channel (int): channel number
seqValueV (float array): values for the voltage (V) one channel in array.
duration (int): waiting time to change to next value in second
Example:
channel = 1
seqValueV = [20.1, 2.5, 13.0, 4, 5, 10.5, 9.5, 22]
seqValueC = [100, 150, 100, 50, 200, 10, 10]
duration = 5
```

SCPI Commands

The XPOW can be controlled using Standard Commands for Programmable Instruments (SCPI) with 115200 baud rates.

Notes: [n] = channel

Description: Constant Voltage Mode Calibration for single channel

Format:

CH: [n]: CALIB: [Voltage Values]: [Current Values]

Description: Set output voltage for single channel Format: CH:[n]:VOLT:[VOLT VALUES] Result: <CH:1:VOLT:[VOLT VALUES]:OK> Example 1: Set the output voltage of channel 1 to 34 V CH:1:VOLT:34 (set the output voltage of channel 1 to max 34 V) Result: <CH:1:VOLT:34:OK> Example 2: Set the output voltage of channel 3 to 20V CH:3:VOLT:20 (set the output voltage of channel 3 to 20 V) Result: <CH:3:VOLT:20:OK> Display real-time data for single channel Format: CH: [n]:VAL? Description: Display voltage and current real-time value of channel n.

Result:

<val:[n]:VOLTAGE VAL:CURRENT VAL>

Example:

CH:1:VAL?

Result:

<val:1:6.101:100.211>

Set output voltage for group of channels

Format:

CH: [m-n]:VOLT: [0-Vmax]

Description: Set output voltage of channel m to channel n to [0 V-34 V].

Note: 1 <= m < n <= Channel Max

Example:

CH:1-10:VOLT:20 (set outputs of channel 1 to channel 10 to 20 Volt)

Set measurement config

Format:

MEAS:VoltConvTime:CurrConvTime:Averaging

Description: Set measurement conversion time in uS and averaging sample count.

Result:

MEASCONF:VoltConvTime:CurrConvTime:Averaging >> OK!

<u>Set pin GPIO</u>

Input

Format:

GPIO:[PIN NAME]

Description: Read the GPIO pin

Example:

GPIO:PD4

Result :

GPIO:PD4

Output - High

Format:

GPIO:[PIN NAME]:HIGH

Description: Set the GPIO pin to high (5V)

Example:

GPIO:PF5:HIGH

Result: GPIO:PF5:HIGH

Output - Low

Format:

GPIO:[PIN NAME]:LOW

Description: Set the GPIO pin to low (0V)

Example:

GPIO:PF5:LOW

Result :

GPIO:PF5:LOW

Retrieve device information

Format:

*IDN?

Description: Get information of the device.

Example:

*IDN?

Result :

*IDN? >> XPOW-120AX-CV-U, Nicslab Ops, Inc.

<u>Set range</u>

Format:

CH: [n]: SVR:[0-3]

Note:

0 -> 5 V

1 -> 10 V

2 -> 20 V

3 -> 34 V

Default: 3

Result:

<CH:[n]:SVR:[RANGE VALUES]:OK>

Example 1: Set range of channel to maximum.

CH:1:SVR:3 (set output of channel 1 to max 34 V)

Result:

<CH:1:SVR:3:OK>

Identify Board Format: Board? Note: Top Board : <BOARD:1:TOP> Middle Board : <BOARD:2:MIDDLE> Bottom Board : <BOARD:3:BOTTOM>

Example 1: Set range of channel to maximum.

Board?

Result:

<BOARD:1:TOP>

5. System Shutdown

This section describes how to shutdown properly the XPOW-120AX-CV-U.

In the case of using GUI, the steps are as follows:

- 1. Set OFF all the channels in the GUI.
- 2. Press the ON/OFF Button in GUI (B1, Figure 4). It will change the color of the button from green to grey.
- 3. Close the GUI application.
- 4. Press button A1 (Figure 3).
- 5. Turn off the DC Power Supply.

In the case of using SCPI Command, the steps are as follows:

- 1. Use setOffAllChannels(120) function to set off the channel used before.
- 2. Press the button A1 (Figure 3).
- 3. Turn off the DC Power Supply

NOTE: Once the soft shutdown occurred, the Green & Blue led will be turned off. To use XPOW-120AX-CV-U after a soft shutdown, just switch off and switch on again (restart) the XPOW-120AX-CV-U.

6. Troubleshooting

| Problem | Cause | Solution |
|---|-----------------------------|---|
| The front end light is off when the switch is turned on | No USB connection | Check USB connection to Laptop/PC |
| The Blue light is off when the software is active or the software freezes | Initialization failed | Restart the software / unplug - plug USB connector/Press Reset Button |
| No channel output detected at device under test | Connection failed | Check the metal pad checkpoint to the intended channel. |
| No USB port detected at device manager | No USB connection | Turn on the XPOW-12AX box before running the application, and check USB connection Check the Arduino Driver if it is installed in the computer. Check to another USB port. |
| Unable to upload the file | File format problem | Make sure the file format is .csv |
| No value after uploading the file | File problem | Check the file content: make sure there is no blank space on each row. |
| Unable to use the Auto Mode feature | File format problem | Check the file format, it should be a .csv file. Check content format. |
| Display value unstable in GUI | Serial Connection Failed | Change the USB cable. Use a low-noise USB cable. |

Table 6. Troubleshooting

Please use the following guidelines to identify a particular problem. If the solution does not rectify the problem, contact us at <u>support@nicslab.com</u>.

7. Warranty

Nicslab warrants the hardware and software designed by Nicslab to work accordingly, fulfilling the highest standard of quality product. Nicslab is not liable for consequential or incidental damages or for errors in subject to misuse, neglect, accident, modification, use in critical operation, or has been soldered or altered in any way outside stated by us or unauthorized maintenance.

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Please do not hesitate to contact us at support@nicslab.com if you would like to have more information on warranty or return and refund policy.

8. Compliance

This product complies with the requirements of the European Union's *Conformite Europenne* (CE) and Restriction of Hazardous Substances in Electrical and Electronic Equipment (RoHS) Directive 2015/863 (RoHS3). The certificates can be accessed <u>here</u>.

9. Contact

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